

# American options in the Heston model with stochastic interest rate

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# Outline

- Heston model with CIR stochastic interest rate
- Numerical example: comparison with Medvedev-Scaillet method (2007) and Longstaff-Schwartz method
- Outline of our approach to jump-diffusion models with regime-switching, stochastic volatility and/or stochastic interest rates

# American put in Heston model with CIR interest rates

## Non-dividend paying stock

The stock dynamics,  $S_t$ , stock volatility,  $\hat{v}_t$ , and the riskless interest rate,  $r_t$ , follow the system of SDE

$$\begin{aligned}\frac{dS_t}{S_t} &= r_t dt + \sqrt{\hat{v}_t} d\hat{W}_{1,t}, \\ d\hat{v}_t &= \hat{\kappa}_v(\hat{\theta}_v - \hat{v}_t)dt + \hat{\sigma}_v \sqrt{\hat{v}_t} dW_{2,t}, \\ dr_t &= \kappa_r(\theta_r - r_t)dt + \sigma_r \sqrt{r_t} dW_{3,t},\end{aligned}$$

where  $\hat{W}_{1,t}$ ,  $W_{2,t}$ ,  $W_{3,t}$  are components of the Brownian motion in 3D, with unit variances. For simplicity, only  $\hat{W}_{1,t}$  and  $W_{2,t}$  are correlated, the correlation coefficient being  $\rho$ . The coefficients  $\hat{\kappa}_v$ ,  $\kappa_r$ ,  $\hat{\theta}_v$ ,  $\theta_r$ ,  $\hat{\sigma}_v$  and  $\sigma_r$  are positive.

A. Medvedev and O. Scaillet (M&S) “Pricing American options under stochastic volatility and stochastic interest rates”, Finance Swiss Institute, Res. Paper (2007)

- M&S: “Up to now, there exist no feasible methodology for pricing American options when volatility and interest rates are stochastic.”
- M&S develop an asymptotic method based on a certain suboptimal exercise rule, which can be regarded as intuitively natural.
- M&S produce a numerical example of Heston model with CIR interest rates, and compare the results with the results obtained by Longstaff-Schwarz algorithm with 200,000 sample paths, 500 time steps and 50 exercise dates.

# American put in Heston model with CIR interest rates

We consider the same example.

The parameters are

$\hat{\kappa}_v = 1.58, \hat{\theta}_v = 0.03, \hat{\sigma}_v = 0.2, \kappa_r = 0.26, \theta_r = 0.04, \sigma_r = 0.08, \rho = -0.26$ , the spot value of the riskless rate is 0.04, the spot stock price is  $S = 100$ , the spot volatility  $v$  and strike  $K$  vary:  $v = 0.04, 0.09, 0.16$ ,  $K = 90, 100, 110$ , and time to expiry is  $T = 1/12, 0.25, 0.5$ .

# American put in Heston model with CIR interest rates

- (AP): prices of the American put calculated using discretization of  $(t, v, r)$ -space and the reduction to a regime-switching model;
- (MC): prices of the American put calculated in Medvedev and Scaillet (2007) using the Longstaff-Schwarz algorithm with 200, 000 sample paths, 500 time steps and 50 exercise dates;
- (MS): prices of the American put, which Medvedev and Scaillet (2007) calculated using their asymptotic method with 5 terms of the asymptotic expansion.

# American put in Heston model with CIR interest rates

$T = 1/12$	$v = 0.04$			$v = 0.09$			$v = 0.16$		
price	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
(AP)	0.0754	2.1378	10.002	0.4037	3.2308	10.356	0.9716	4.3325	11.059
(MS)	0.076	2.135	10	0.403	3.228	10.353	0.97	4.329	11.056
(MC)	0.075	2.15	10.018	0.404	3.238	10.352	0.969	4.341	11.065
relative	$v = 0.04$			$v = 0.09$			$v = 0.16$		
difference	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
$\epsilon(AP, MS)$	-0.0076	0.0013	0.0002	0.0018	0.0009	0.0003	0.0016	0.0008	0.0003
$\epsilon(AP, MC)$	0.0056	-0.0057	-0.0016	-0.0007	-0.0022	0.0004	0.0027	-0.0020	-0.0006
$\epsilon(MS, MC)$	0.0133	-0.0070	-0.0018	-0.0025	-0.0031	0.0001	0.0010	-0.0028	-0.0008

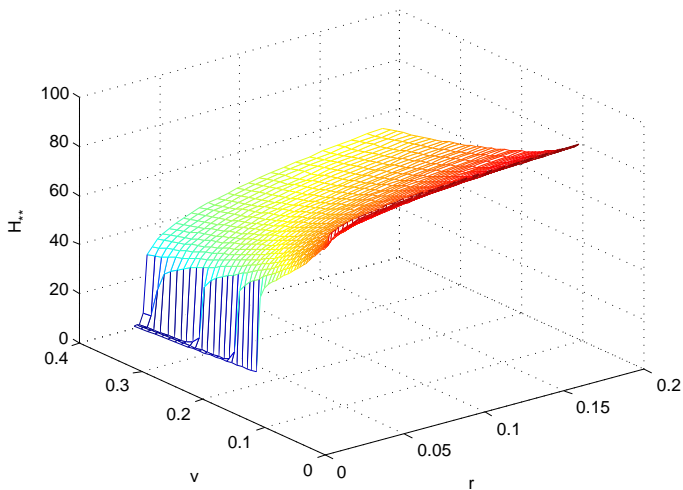
$T = 0.25$	$v = 0.04$			$v = 0.09$			$v = 0.16$		
price	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
(AP)	0.6131	3.4650	10.321	1.6216	5.1758	11.548	2.9077	6.9254	13.096
(MS)	0.612	3.459	10.312	1.619	5.169	11.537	2.904	6.919	13.085
(MC)	0.621	3.462	10.308	1.627	5.171	11.573	2.903	6.936	13.063
relative	$v = 0.04$			$v = 0.09$			$v = 0.16$		
difference	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
$\epsilon(AP, MS)$	0.0019	0.0017	0.0009	0.0016	0.0013	0.0010	0.0013	0.0009	0.0008
$\epsilon(AP, MC)$	-0.0127	0.0009	0.0013	-0.0033	0.0009	-0.0022	0.0016	-0.0015	0.0025
$\epsilon(MS, MC)$	-0.0145	-0.0009	0.0004	-0.0049	-0.0004	-0.0031	0.0003	-0.0025	0.0017

# American put in Heston model with CIR interest rates

(cont-d)

$T = 0.5$	$\nu = 0.04$			$\nu = 0.09$			$\nu = 0.16$		
price	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
(AP)	1.3615	4.5737	10.896	2.8290	6.6689	12.708	4.5809	8.8552	14.807
(MS)	1.357	4.559	10.879	2.822	6.654	12.68	4.575	8.84	14.781
(MC)	1.351	4.578	10.912	2.819	6.678	12.678	4.573	8.843	14.785
relative	$\nu = 0.04$			$\nu = 0.09$			$\nu = 0.16$		
difference	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$	$K = 90$	$K = 100$	$K = 110$
$\epsilon(AP, MS)$	0.0033	0.0032	0.0015	0.0025	0.0022	0.0022	0.0013	0.0017	0.0017
$\epsilon(AP, MC)$	0.0078	-0.0009	-0.0015	0.0035	-0.0014	0.0023	0.0017	0.0014	0.0015
$\epsilon(MS, MC)$	0.0044	-0.0042	-0.0030	0.0011	-0.0036	0.0002	0.0004	-0.0003	-0.0003

# Early exercise threshold



# Scheme of the method

## General set-up:

- regime-switching model, finite number of states
- in each state  $j$ , a 2-3 factor process  $(X_t^{(j)}, Y_t^{(j)})$
- $Y_t^{(j)}$  is a mean-reverting process, which defines the dynamics of the interest rate and/or volatility
- jump-diffusion innovations in  $X_t^{(j)}$  are independent of innovations in  $Y_t^{(j)}$ , and both are independent of the modulating Markov chain
- drift of  $X_t^{(j)}$  depends on  $Y_t^{(j)}$
- log-stock price  $\log S_t^{(j)} = X_t^{(j)} +$  affine or quadratic function of  $Y_t^{(j)}$

## Basic examples:

- $Y_t^{(j)}$  (or its components) are of the OU-type or CIR-type, with embedded jumps
- interest rate and/or volatility are affine or quadratic function of  $Y_t^{(j)}$
- SDE for  $X_t^{(j)}$  is of the form

$$dX_t^{(j)} = \mu^{(j)}(Y_t^{(j)})dt + \sigma(Y_t^{(j)})dZ_t^{(j)}$$

where  $Z_t^{(j)}$  is a Lévy process

## General scheme of solution. Part I.

In each state of the modulating Markov chain

- discretize the state space for and the infinitesimal generator of  $Y_t^{(j)}$
- freeze the riskless rate and coefficients in SDE for  $X_t^{(j)}$  at points of the discretized state space
- truncate the discretized state space for  $Y_t^{(j)}$
- impose appropriate boundary conditions so that the discretized part of the infinitesimal generator can be interpreted as the infinitesimal generator of a Markov chain

## General scheme of solution. Part II.

- Apply to the resulting regime-switching Lévy model (with a larger modulating Markov chain) a natural generalization of the method of lines (equivalently, Carr's randomization method)
- Carr's randomization reduces the pricing of an American option with finite time horizon to a sequence of perpetual options in regime-switching models
- Apply to each perpetual option in the sequence an iteration procedure
- The main building block of the iteration procedure is a general optimal stopping theorem for American and real options in Lévy models based on the Wiener-Hopf method

# Non-switching Lévy models

## Notation

- $q > 0$  – the riskless rate
- $X = \{X_t\}_{t \geq 0}$  – a Lévy process
- $\Psi$  – Lévy exponent of  $X$
- $L$  – infinitesimal generator of  $X$
- $g(X_t)$  – payoff stream
- $G(X_t)$  – instantaneous payoff
- $x$  – the current realization of  $X$
- $E^x[f(X_t)] := E[f(X_t) | X_0 = x]$

# Non-switching Lévy models

## Moment generating function of a Lévy process

$$E \left[ e^{zX_t} \right] = e^{t\Psi(z)}$$

$$Le^{zx} = \Psi(z)e^{zx}$$

Lévy process with jump component of finite variation: infinitesimal generator and Lévy Khintchine formula.  $b$  – drift,  $\sigma^2$  – variance,  $F(dy)$  – density of jumps

$$Lu(x) = \frac{\sigma^2}{2} u''(x) + bu'(x) + \int_{-\infty}^{+\infty} (u(x+y) - u(x)) F(dy)$$

$$E \left[ e^{zX_t} \right] = \exp \left[ t \left( \frac{\sigma^2}{2} z^2 + bz + \int_{-\infty}^{+\infty} (e^y - 1) F(dy) \right) \right]$$

# Perpetual American options

Find the optimal stopping time  $\tau$  which maximizes

$$V(x; \tau) = E^x \left[ \int_0^\tau e^{-qt} g(X_t) dt \right] + E^x \left[ e^{-r\tau} G(X_\tau) \right].$$

- Can be reduced to the case  $G = 0$ .
- In many cases,  $\tau$  is the hitting time of a semi-infinite interval.
- Explicit formula for  $V(x; \tau)$  and equation for the optimal exercise threshold are available provided  $g$  is monotone and changes sign (after reduction to the case  $G = 0$ ).
- **At each step of the backward induction, each step of the iteration procedure, and for each state, we will solve an optimal stopping problem of this form**

# Regime-switching models

## General set-up and notation

- finite state Markov chain
- $\lambda_{jk}$  - transition rates;  $\Lambda_j = \sum_{k \neq j} \lambda_{jk}$
- $X_t^{(j)}$  - Lévy process in state  $j$
- $\Psi_j$  and  $L_j$ : Lévy exponent and infinitesimal generator of  $X_t^{(j)}$
- $q_j$  - state- $j$  riskless rate
- $g_j$  - payoff stream in state  $j$
- $G_j$  - instantaneous payoff in state  $j$

# Regime-switching models. Finite time horizon

Assumptions: for  $j = 1, \dots, m$ ,

- (i) the payoff functions  $G_j$  decrease and change sign;
- (ii)  $L_j G_j$  is well-defined;
- (iii)  $\tilde{g}_j = \sum_{k \neq j} \lambda_{jk} G_k - (q_j + \Lambda_j - L_j) G_j$  does not decrease, and  $\tilde{g}_j(-\infty) < 0$

Example: for  $G_j(x) = K_j - B_j e^x$

- (i)  $B_j, K_j > 0$ ;
- (ii)  $E \left[ \exp(X_1^{(j)}) \right] < \infty$ ;
- (iii)  $\sum_{k \neq j} \lambda_{jk} (K_k / K_j - 1) - q_j < 0 \leq \sum_{k \neq j} \lambda_{jk} (1 - B_k / B_j) + (q_j - \Psi_j(1))$

**The RHS: minus the rate of instantaneous discounted gains**

# First step of Algorithm

1. Choose  $(0 =) t_0 < t_1 < \dots < t_N (= T)$ .
2. For  $s = N - 1, N - 2, \dots$ , set  $\Delta_s = t_{s+1} - t_s$ ,  $q_j^s = q_j + \Lambda_j + \Delta_s^{-1}$
3. Set  $v_{j,*}^N(x) = G_j(x)_+$ ,  $j = 1, 2, \dots, m$ .
4. For  $s = N - 1, N - 2, \dots$ , denote by  $v_{j,*}^s$  and  $h_{j,*}^s$  the Carr's randomization approximations to state- $j$  option value and exercise boundary for interval  $[t_s, t_{s+1})$ .

# Backward induction and iteration procedure

- for  $s = l < N$ , calculate the (approximations to the) exercise boundaries  $h_{j,*}^s$  and option values  $v_{j,*}^s$ ,  $j = 1, 2, \dots, m$ , assuming that for  $l + 1 \leq s \leq N$  and  $j = 1, 2, \dots, m$ ,  $h_{j,*}^s$  and  $v_{j,*}^s$  are known
- for each  $s = N - 1, N - 2, \dots$  and  $j = 1, 2, \dots, m$ , construct sequences  $\{h_j^{sn}\}_{n=0}^{\infty}$  and  $\{v_j^{sn}\}_{n=0}^{\infty}$ , s.t.

$$h_{j,*}^s = \lim_{n \rightarrow +\infty} h_j^{sn}, \quad v_{j,*}^s = \lim_{n \rightarrow +\infty} v_j^{sn} \quad (1)$$

Thus, for each  $s$ , we need to introduce an additional cycle in  $n$ ; and inside the cycle in  $n$ , we use additional cycles in  $j = 1, 2, \dots, m$ .

At step  $s = N - 1, N - 2, \dots$

- set  $v_j^{s0} = 0, h_j^{s0} = +\infty, j = 1, \dots, m,$
- for  $n = 1, 2, \dots,$  and  $j = 1, 2, \dots, m,$  find an optimal  $\tau_j^{sn,-}$ , which maximizes

$$v_j^{sn}(x) = E^{j,x} \left[ \int_0^{\tau_j^{sn,-}} e^{-q_j^s t} (\Delta_s^{-1} v_{j,*}^{s+1}(X_t^{(j)}) + \sum_{k \neq j} \lambda_{jk} v_k^{s,n-1}(X_t^{(j)})) dt \right] \\ + E^{j,x} \left[ e^{-q_j^s \tau_j^{sn,-}} G_j(X_{\tau_j^{sn,-}}^{(j)}) \right].$$

We find  $\tau_j^{sn,-}$  as the hitting time of the unique interval of the form  $(-\infty, h_j^{sn}]$  solving the problem in *non-regime-switching Lévy model*

## Main technical tools

- expected present value operators (EPV-operators) under a Lévy process and its supremum and infimum processes
- Wiener-Hopf factorization
- general theorem about optimal timing to abandon a monotone stream that is a monotone function of a Lévy process

# Wiener-Hopf factorization

## Supremum and infimum processes

- $\bar{X}_t = \sup_{0 \leq s \leq t} X_s$  - the supremum process
- $\underline{X}_t = \inf_{0 \leq s \leq t} X_s$  - the infimum process

## Normalized EPV operators under $X$ , $\bar{X}$ , and $\underline{X}$ :

- $$(\mathcal{E}g)(x) := qE^x \left[ \int_0^{+\infty} e^{-qt} g(X_t) dt \right]$$

- $$(\mathcal{E}^+g)(x) := qE^x \left[ \int_0^{+\infty} e^{-qt} g(\bar{X}_t) dt \right],$$

- $$(\mathcal{E}^-g)(x) := qE^x \left[ \int_0^{+\infty} e^{-qt} g(\underline{X}_t) dt \right].$$

# Wiener-Hopf factorization formula

Three versions:

1.  $T \sim \text{Exp}(q)$  – the exponential random variable of mean  $q^{-1}$ , independent of process  $X$ . For  $z \in i\mathbf{R}$ ,

$$E[e^{zX_T}] = E[e^{z\bar{X}_T}]E[e^{z\underline{X}_T}];$$

2. For  $z \in i\mathbf{R}$ ,

$$\frac{q}{q - \Psi(z)} = \kappa_q^+(z)\kappa_q^-(z);$$

3.  $\mathcal{E} = \mathcal{E}^- \mathcal{E}^+ = \mathcal{E}^+ \mathcal{E}^-$ .

1 and 2 are the same, 3 is valid in the space of locally bounded measurable function which do not grow too fast at infinity

# Example 1: Brownian motion with variance $\sigma^2$ and drift $b$

The Lévy exponent is

$$\Psi(z) = \frac{\sigma^2}{2} z^2 + bz$$

EPV-operators are of the form

$$\mathcal{E}^+ u(x) = \beta^+ \int_0^{+\infty} e^{-\beta^+ y} u(x+y) dy,$$

$$\mathcal{E}^- u(x) = (-\beta^-) \int_{-\infty}^0 e^{-\beta^- y} u(x+y) dy,$$

where  $\beta^- < 0 < \beta^+$  are the roots of the “characteristic equation”

$$q - \Psi(\beta) = 0.$$

## Example 2: Kou's model

### The Lévy exponent

$$\Psi(z) = \frac{\sigma^2}{2} z^2 + bz + \frac{c^+ z}{\lambda^+ - z} + \frac{c^- z}{\lambda^- - z}.$$

### EPV-operators are of the form

$$\mathcal{E}^+ u(x) = \sum_{j=1,2} a_j^+ \beta_j^+ \int_0^{+\infty} e^{-\beta_j^+ y} u(x+y) dy,$$

$$\mathcal{E}^- u(x) = \sum_{j=1,2} a_j^- (-\beta_j^-) \int_{-\infty}^0 e^{-\beta_j^- y} u(x+y) dy,$$

where  $\beta_2^- < \lambda^- < \beta_1^- < 0 < \beta_1^+ < \lambda^+ < \beta_2^+$  are the roots of the “characteristic equation”  $q - \Psi(\beta) = 0$ , and  $a_j^\pm > 0$  are constants.

# Option to abandon a non-decreasing stream.

## Objective:

Find an optimal stopping time  $\tau$

$$V(x) = \sup_{\tau} E^x \left[ \int_0^{\tau} e^{-qt} g(X_t) dt \right]$$

In many cases, for non-decreasing  $g$ , the optimal stopping time is the hitting time of a semi-infinite interval  $(-\infty, h]$ . Notation:  $\tau_h^-$ .

## Theorem 1

Let  $X$  satisfy the (ACP)-property, and let  $g$  be a measurable locally bounded function satisfying certain regularity conditions. Then for any  $h$ ,

$$V(x; h) = q^{-1} \mathcal{E}^{-1} \mathbf{1}_{(h, +\infty)} \mathcal{E}^+ g(x). \quad (2)$$

## Corollary.

A natural candidate for the optimal exercise boundary is  $h_*$  s.t.

$$\mathcal{E}^+ g(h_*) = 0. \quad (3)$$

## Theorem 2

Assume, in addition, that  $g$  is monotone and changes sign. Then

- (i) equation  $\mathcal{E}^+g(h_*) = 0$  has a unique solution;
- (ii)  $\tau_{h_*}^-$  is an optimal stopping time, and  $h_*$  is the unique optimal threshold;
- (iii) the rational value of the stream (with the option to abandon it) is

$$V_*(x) = q^{-1}\mathcal{E}^-\mathbf{1}_{(h_*,+\infty)}\mathcal{E}^+g(x); \quad (4)$$

- (iv) there exists a non-increasing function  $W_*$  which is non-negative below  $h_*$  and 0 above  $h_*$  such that  $V_* = \mathcal{E}(W_* + g)$ .